16-day BRDF/Albedo from L2Glite vs L2G-heavy

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Algorithm Updates and Expected Differences

Code Changes

- L2G-lite (PGE13)
 - Stores one observation per orbit
 - Ensures same state QA for an observation as in L2G-heavy
- BRDF/Albedo (PGE23)
 - L2G-lite version of BRDF is updated to use all available L2G observations, L2G-heavy version of BRDF limits to 4 observations/day, but from different orbits.
 - In L2G-heavy version of BRDF observation from an orbit is a weighted average of 2 or more observations when more than 2 observations are available. In L2G-light an observation is a sample from an orbit.

Expected difference in BRDF product

- Strong differences are expected at high latitude. L2G-lite version of BRDF/albedo will have a better spatial coherence.
- Do not expect identical result even in tiles close to equator, there could be small difference in reflectance input to inversion algorithm – average of observations (L2G_heavy) vs one sample observation (L2G-lite).
- Smooth, sharp and narrow 2D scatter plots of parameters from the two difference versions (mostly with in 1% error margin – depends on sensitivity of inversion algorithm to difference in input)

Science Test

Science Test

- 16-day period global test (starting day 2003193)
- Baseline (AS 230)
 - C5 Operational BRDF/Albedo using C5 operational version of L2G-heavy
 - C5 Operational MOD09A1 using C5 operational version of L2G-lite
- Test (AS 243)
 - C5 (non-operational) BRDF/Albedo version using the C5 new version of L2Glite
 - C5 Operational MOD09A1 using the C5 new version of L2G-lite

Data used in this analysis

- MOD09A1
 - h09v05 (Northwest America)
 - h20v11 (South Africa)
- MCD43A4 (NBAR) from day 2003193 and tiles
 - h20v11 (South Africa 20 30 deg latitude)
 - h09v05 (Northwest America, 30 40 deg latitude)
 - h16v01 (Greenland, 70 80 deg latitude)

Analysis of MOD09A1

Algorithm Change Verification

- No change in MOD09A1 (PGE21) PGE. The test and baseline use operational C5 version of the PGE which uses L2G-lite as input.
- Baseline used the operational L2G-lite and the test used the new version of the L2G-lite.
- In the new version of the L2G-lite pointers to the 1km observations might have changed for some of the 500m reflectance observations. This is most likely to happen and visible at the edge of cloud and aerosol patches.
- The change in these atmospheric states causes the MOD09A1 algorithm to pick observations from a different day.

Analysis of MOD09A1: 2003193, h09v05 (1/4)

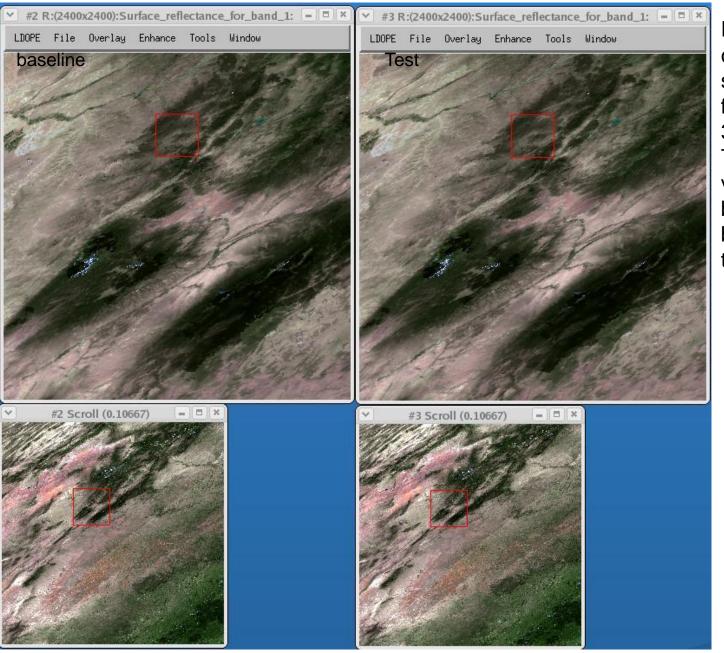


Figure shows RGB composite images of surface reflectance from bands 1, 4, and 3.

There isn't any visible differences between the baseline and the test data.

Analysis of MOD09A1: 2003193, h09v05 (2/4)

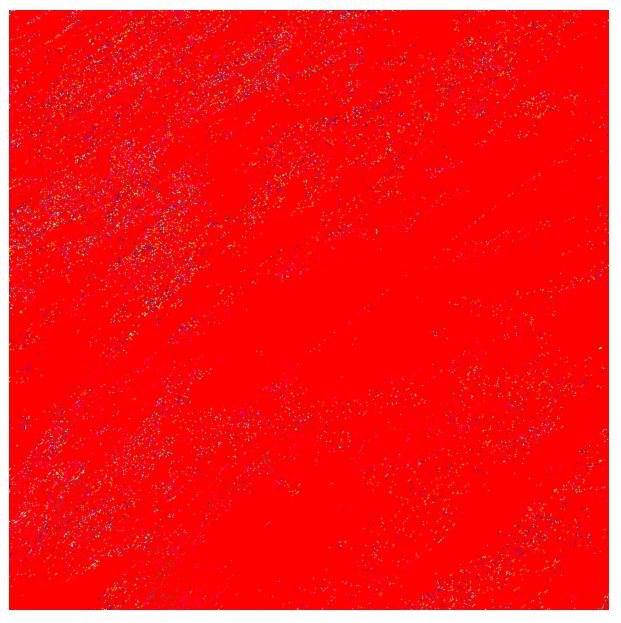
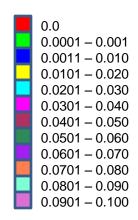
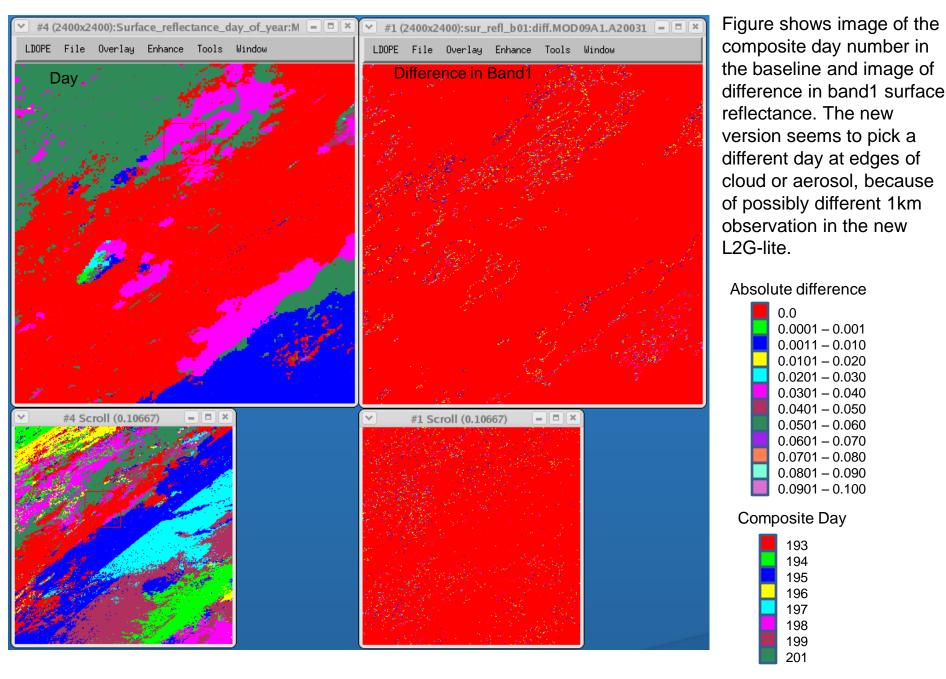


Figure shows the absolute difference in band1 surface reflectance between the baseline and test version of data. The two data versions are mostly identical except for pixels at edges of the cloud and aerosol. The difference in reflectance at these pixels could be significant since they now come from a different data day with different viewing geometry.



Analysis of MOD09A1: 2003193, h09v05 (3/4)



Analysis of MOD09A1: 2003193, h09v05 (4/4)

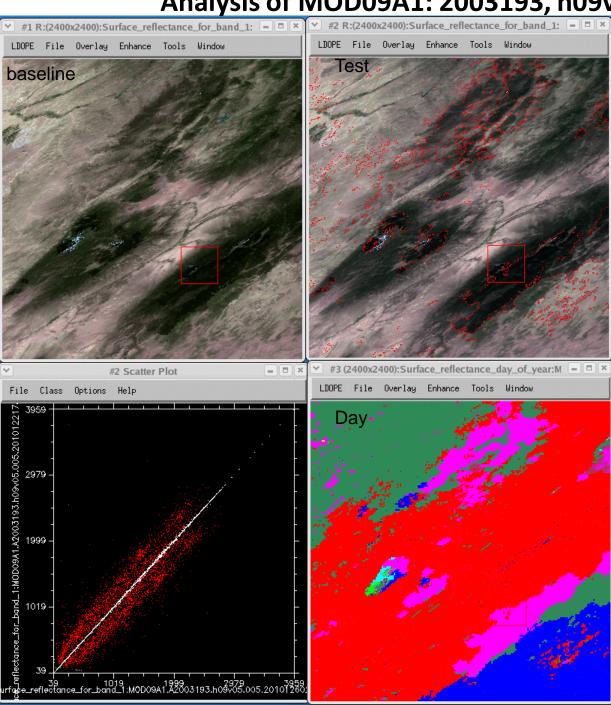
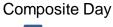


Figure shows RGB composite images from bands 1, 4, and 3, the scatter plot of band1 surface reflectance and the composite data day from the baseline.

The pixels labeled red in the RGB image from the test version of data corresponds to red points in the scatter plot. These pixels are mostly at edges where the composite day changes because of the different 1km observation in the L2G-lite.





Analysis of MOD09A1: 2003193, h20v11 (1/4)

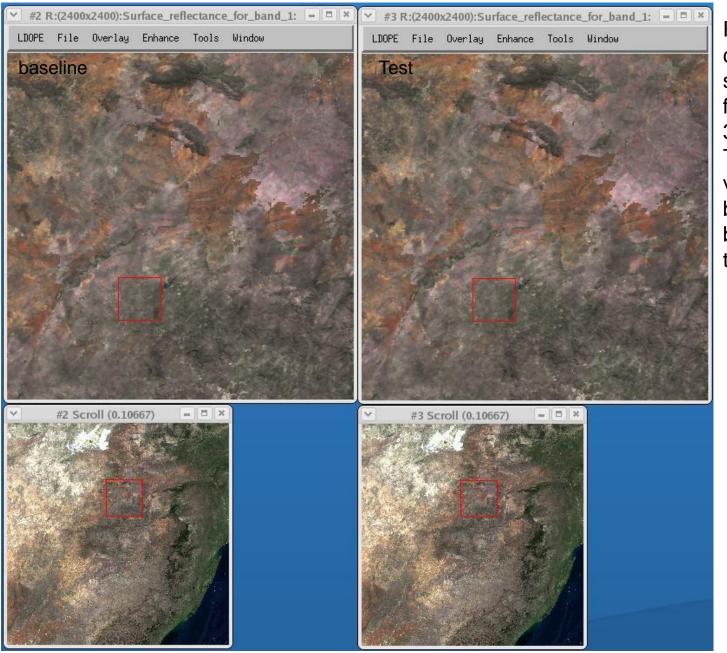


Figure shows RGB composite images of surface reflectance from bands 1, 4, and 3

There isn't any visible differences between the baseline and the test data.

Analysis of MOD09A1: 2003193, h20v11 (2/4)

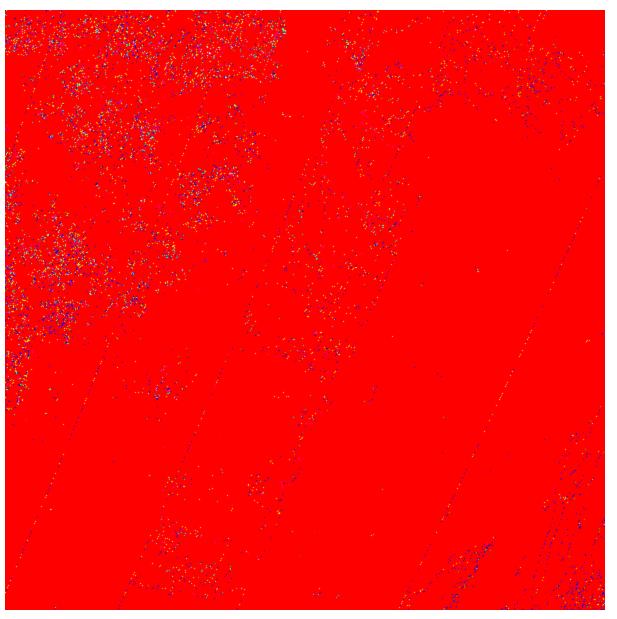
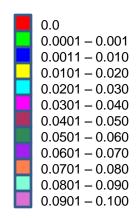
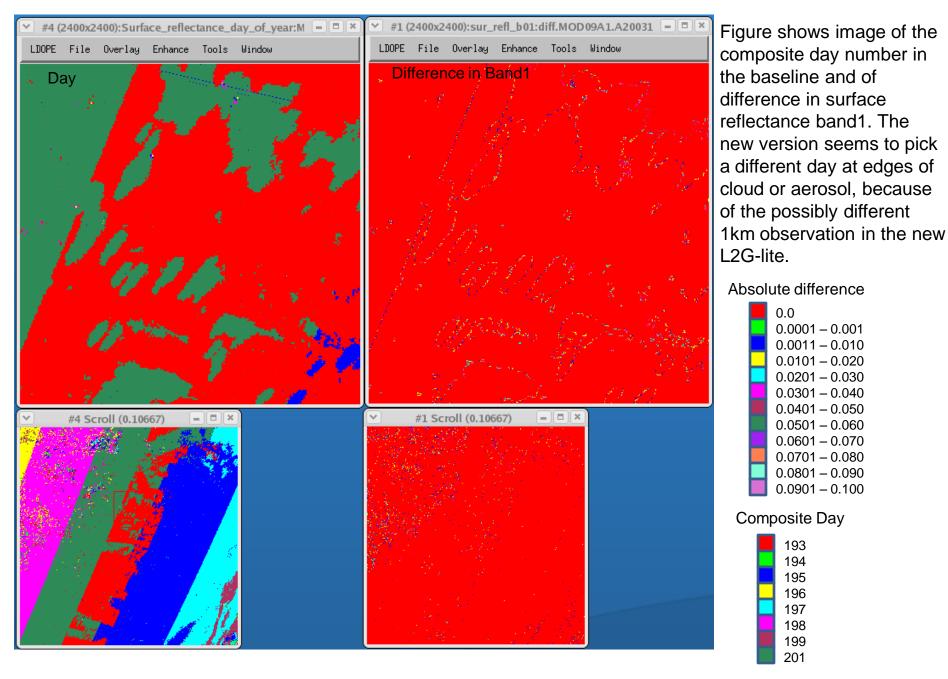


Figure shows the absolute difference in band1 surface reflectance between the baseline and test version of data. The two data versions are mostly identical except for pixels at edges of the cloud and aerosol. The difference in reflectance at these pixels could be significant since they now come from a different data day with different viewing geometry.



Analysis of MOD09A1: 2003193, h20v11(3/4)



Analysis of MOD09A1: 2003193, h20v11(4/4)

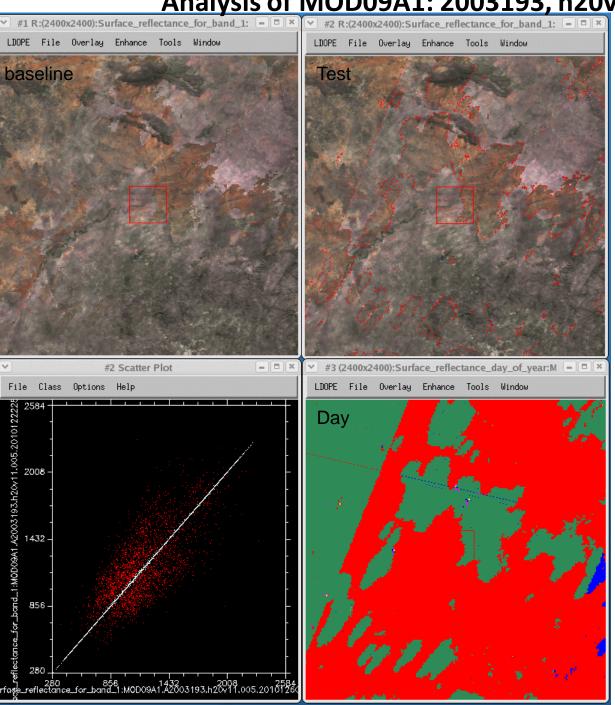
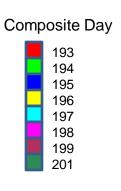


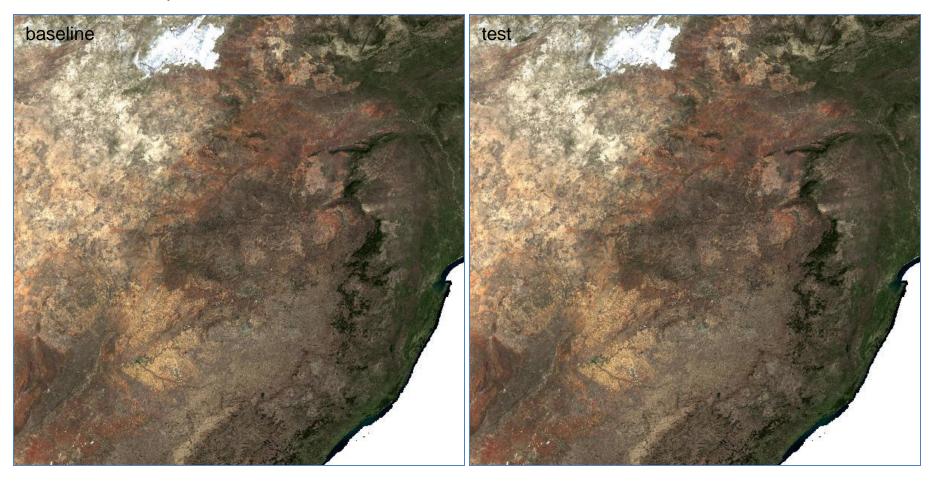
Figure shows RGB composite images from bands 1, 4, and 3, the scatter plot of band1 surface reflectance and the composite data day from the baseline.

The pixels labeled red in the RGB image from the test version of data corresponds to red points in the scatter plot. These pixels are mostly at edges where the composite day changes because of the different 1km observation in the L2G-lite.



Analysis of BRDF/Albedo: MCD43A4, 2003193, h20v11

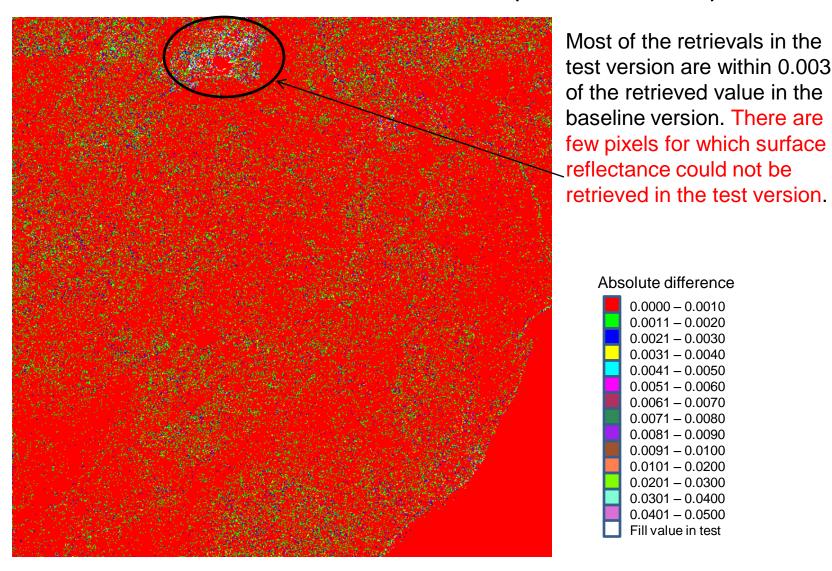
RGB composite from bands 1, 3 and 4

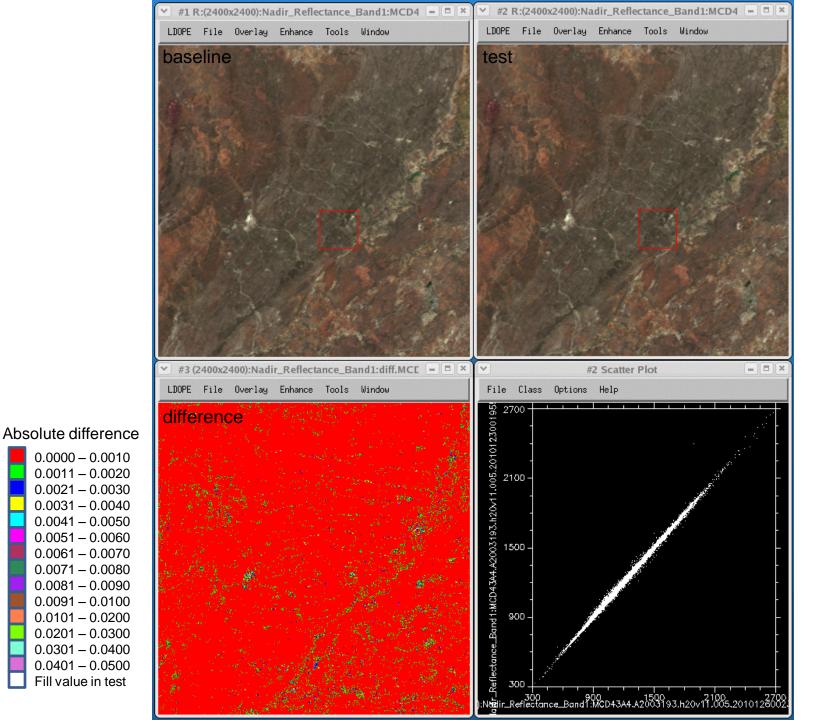


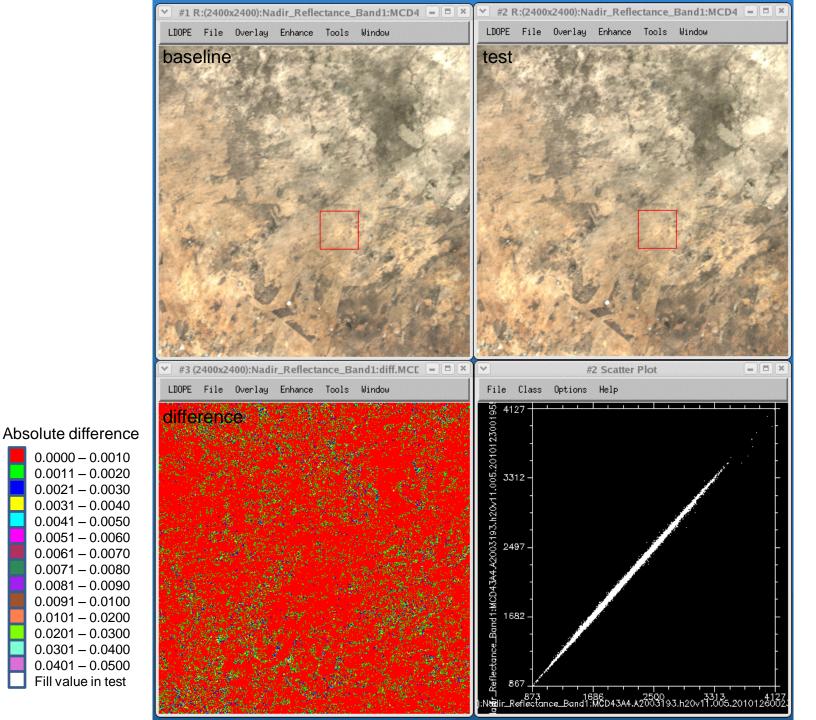
 Difference between the two version is hardly visible. following slides shows the full tile difference image followed by many spatial subsets of the two data versions, difference image and the 2D scatter plot band1 reflectance.

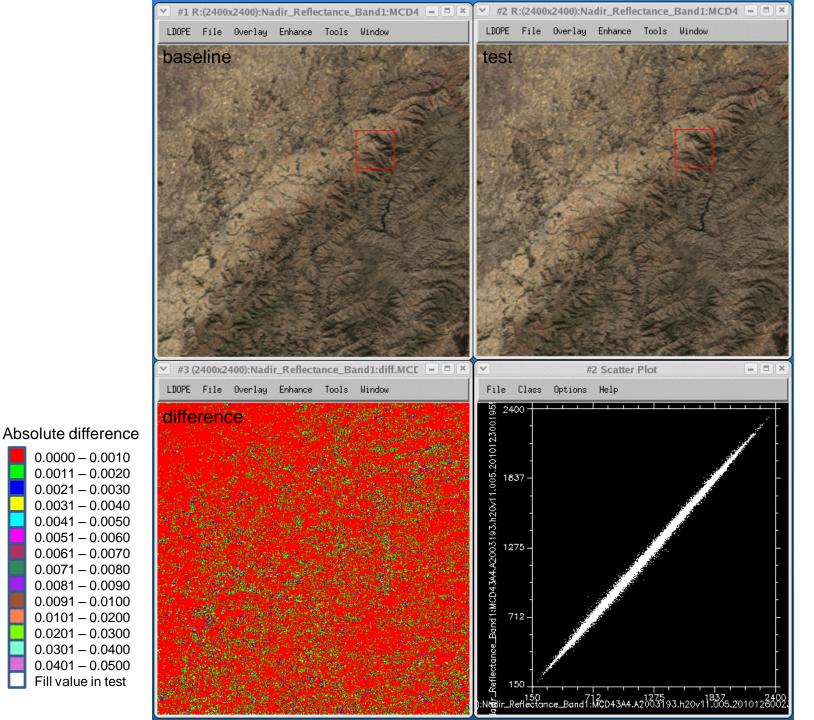
Analysis of BRDF/Albedo: MCD43A4, 2003193, h20v11

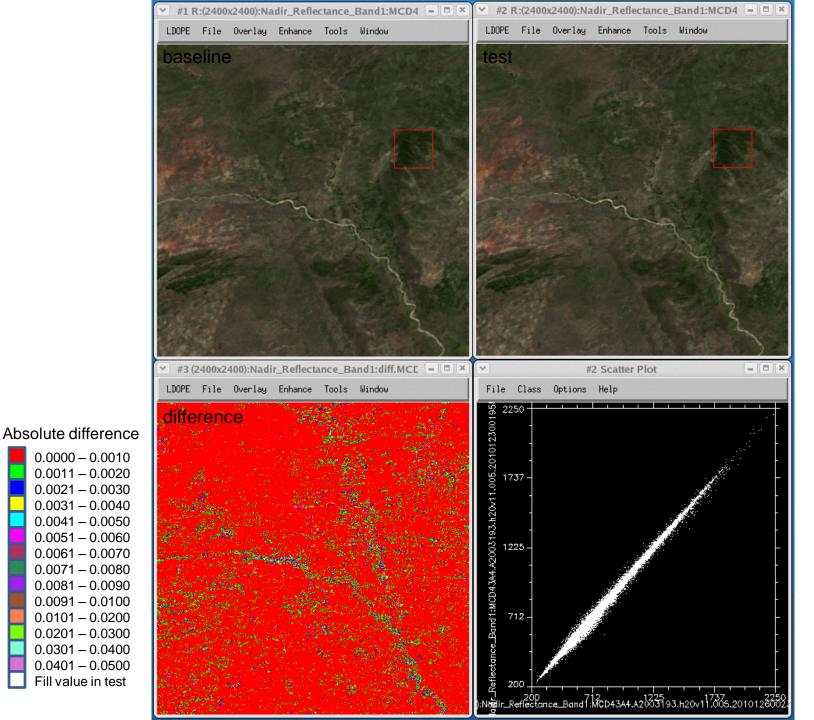
Absolute difference in NBAR – band1 (baseline – test)

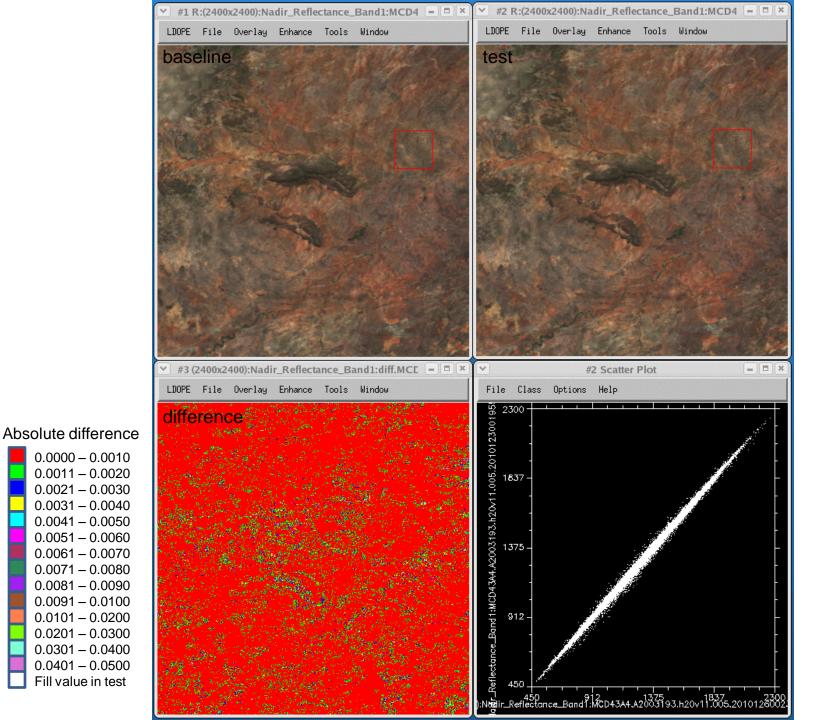


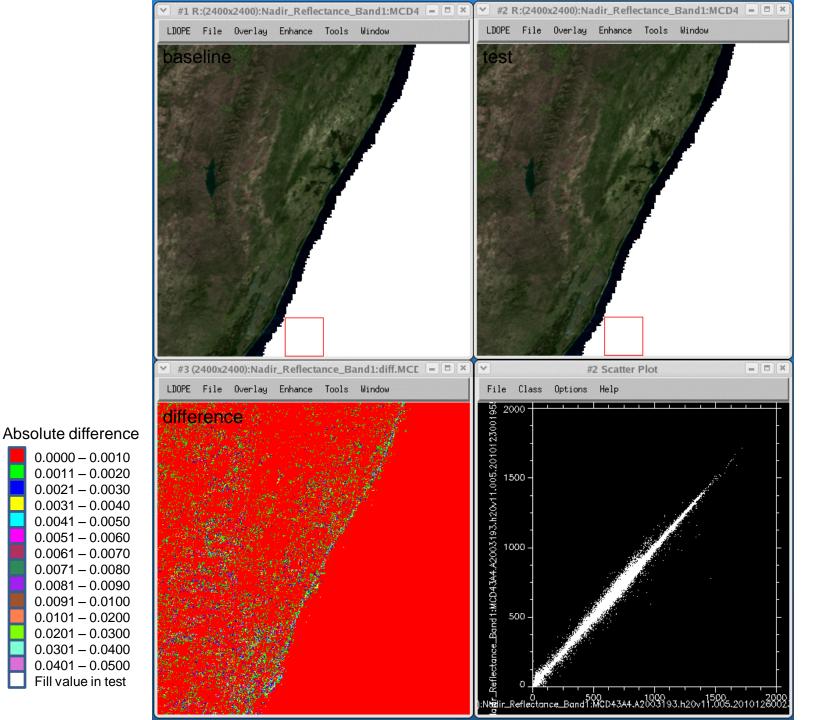






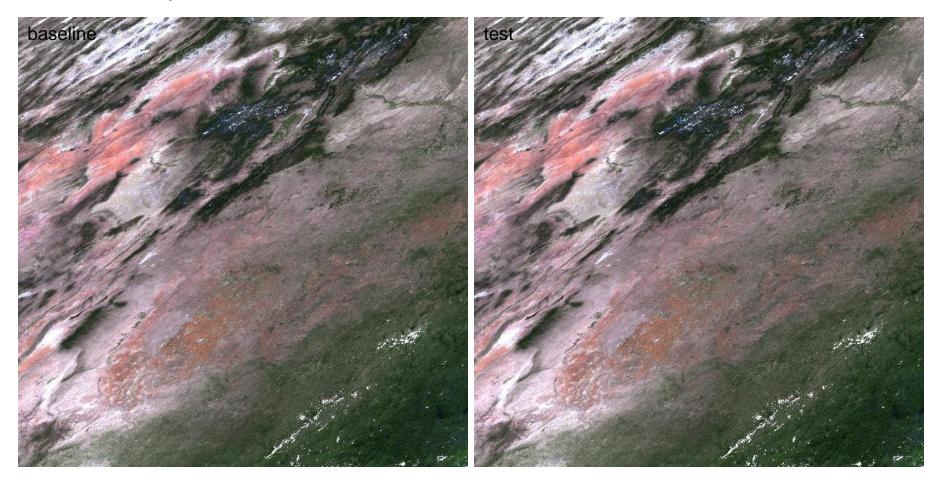






Analysis of BRDF/Albedo: MCD43A4, 2003193, h09v05

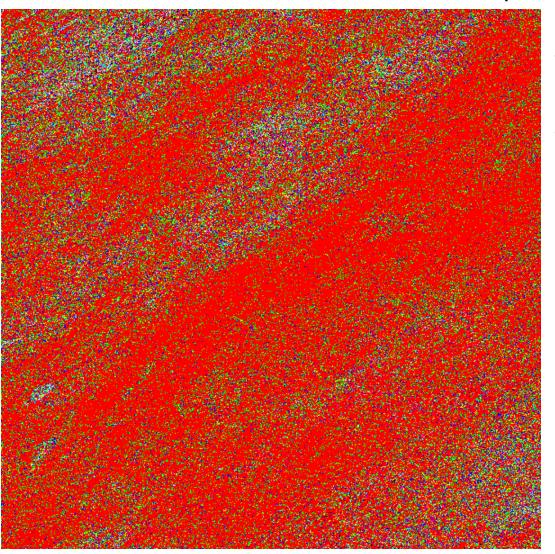
RGB composite from bands 1, 3 and 4



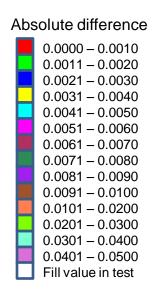
• Difference between the two version is hardly visible except at the edges of the cloud. Following slides shows the full tile difference image followed by many spatial subsets of the two data versions, difference image and the 2D scatter plot band1 reflectance.

Analysis of BRDF/Albedo: MCD43A4, 2003193, h09v05

Absolute difference in NBAR – band1 (baseline – test)

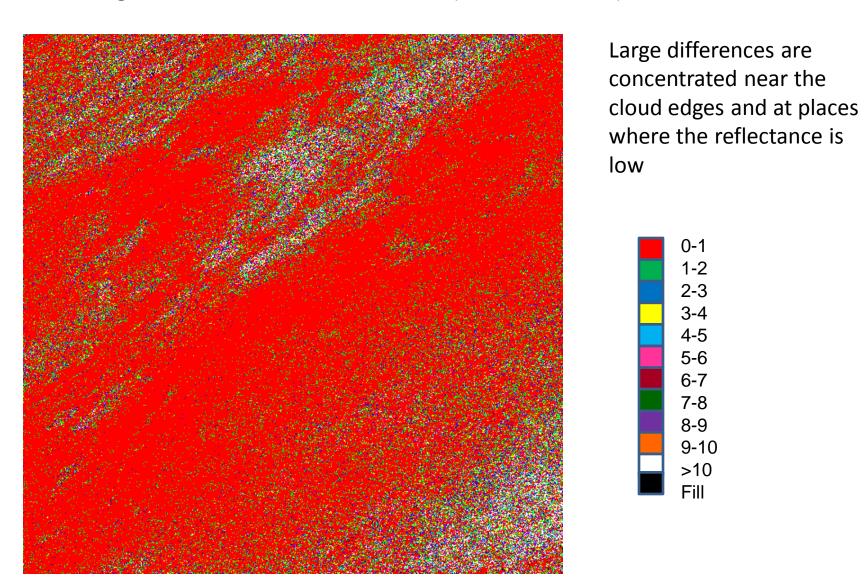


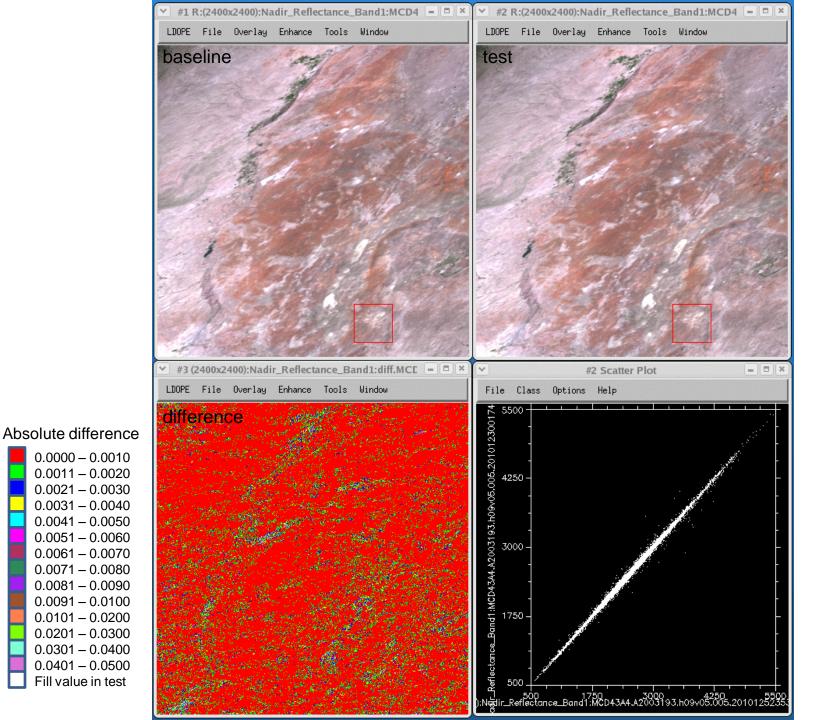
Most of the retrievals in the test version are within 0.006 of the retrieved value in the baseline version. There are few pixels for which surface reflectance could not be retrieved in the test version mostly around the cloudy area.

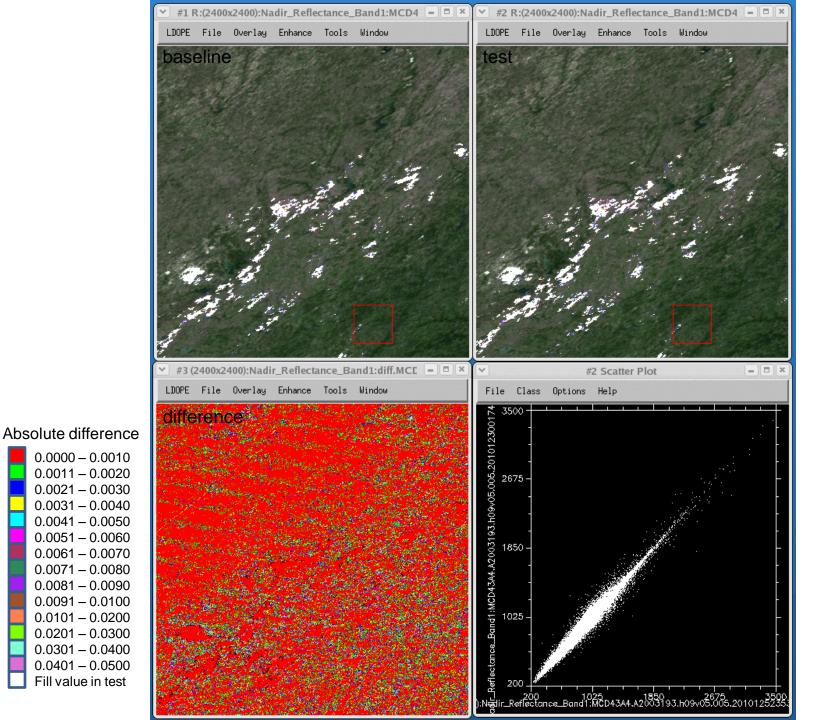


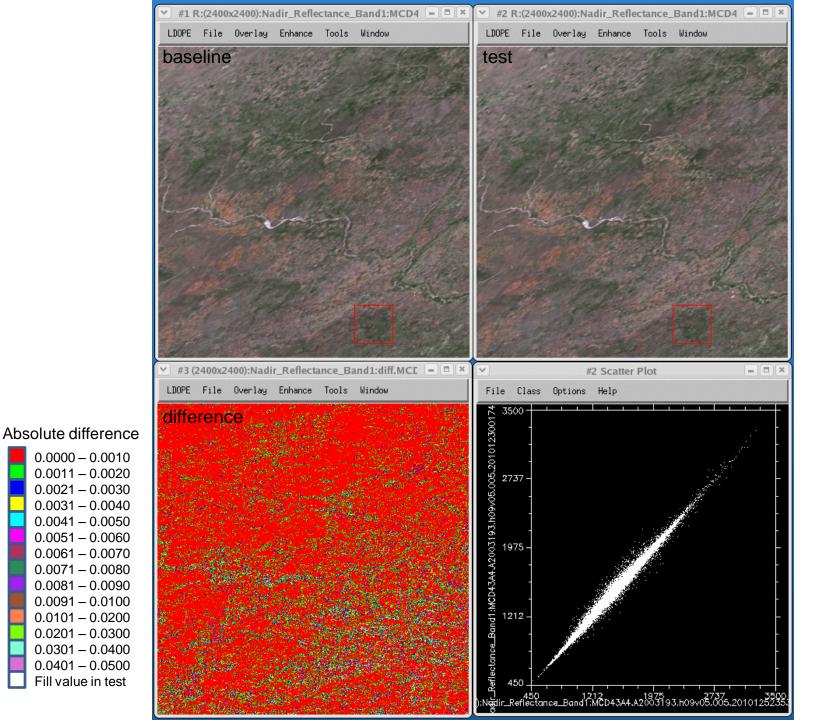
Analysis of BRDF/Albedo: MCD43A4, 2003193, h09v05

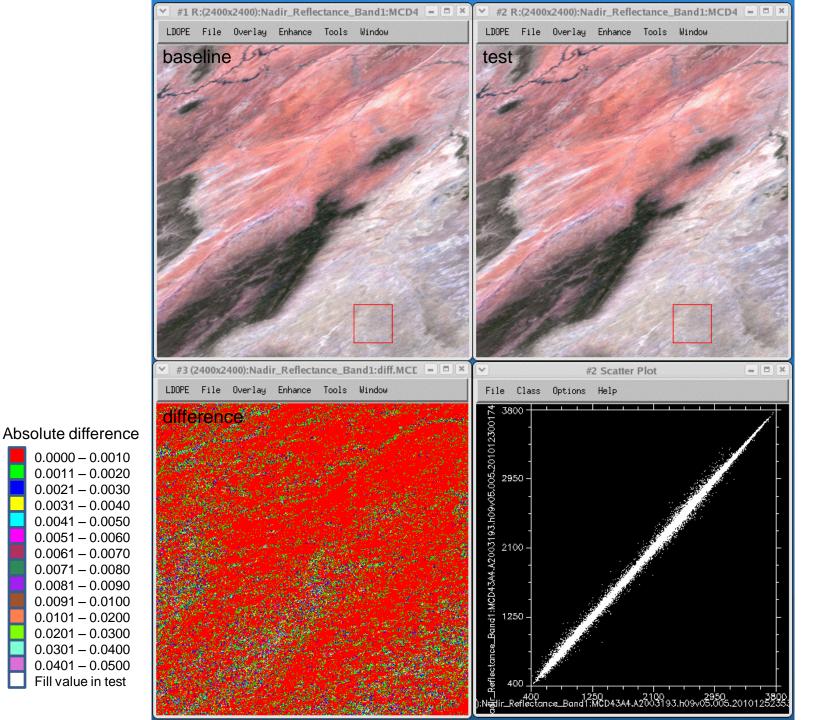
Percentage relative difference in band1 (baseline – test)/baseline

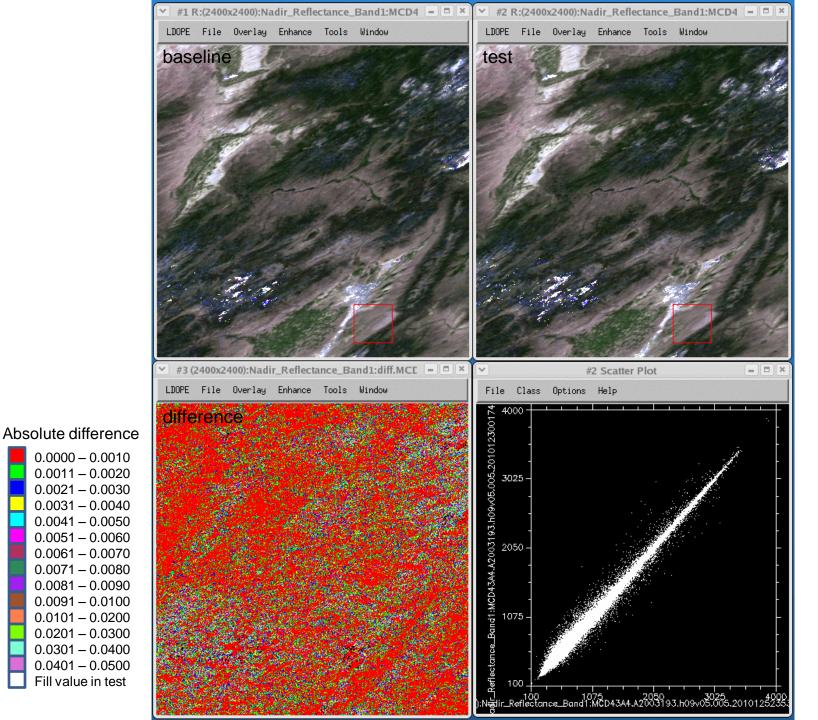


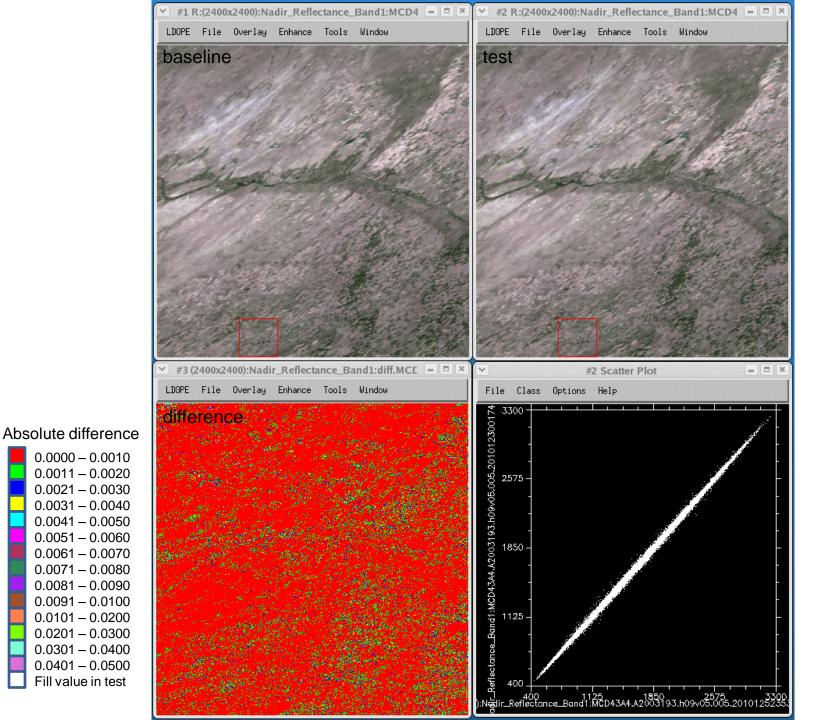






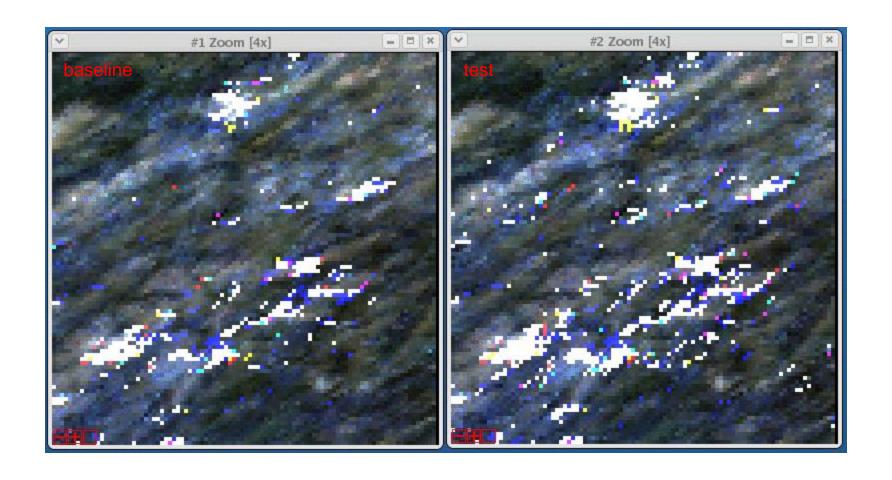






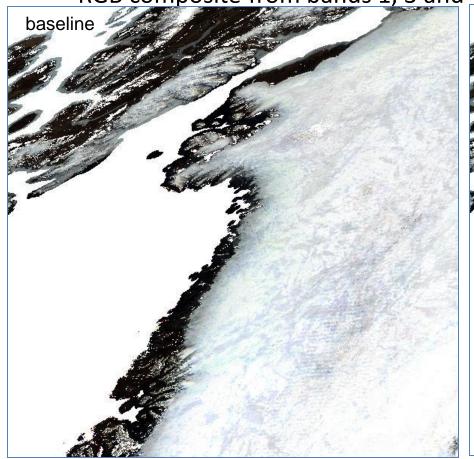
Day 2003193, tile h09v05

 Following example subset images show few pixels at the edges of the cloud that could not be retrieved in the test version.



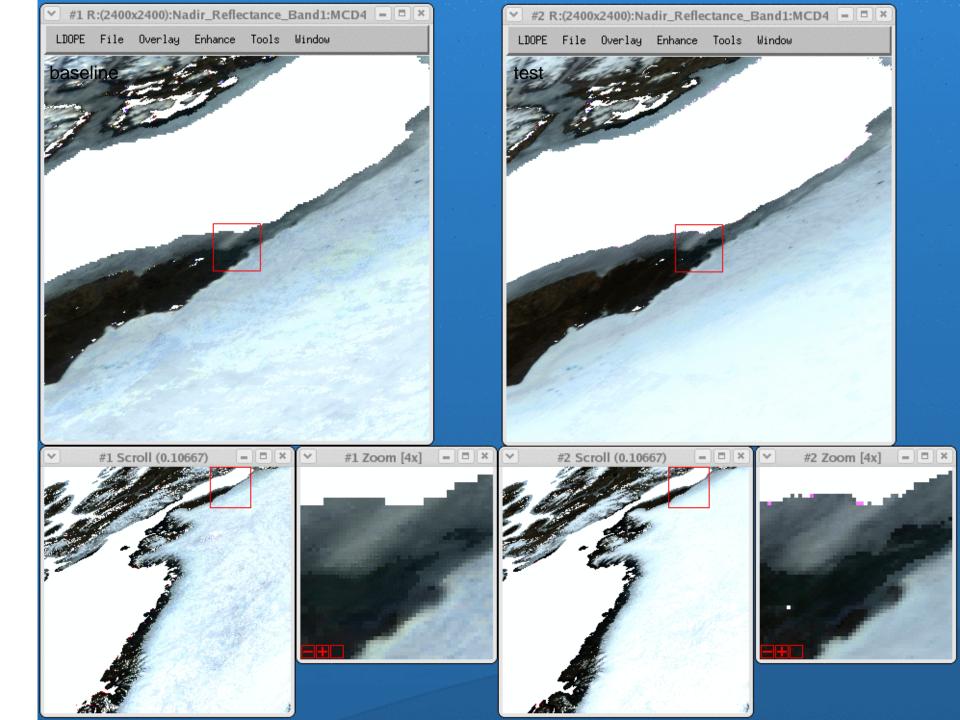
Analysis of BRDF/Albedo: MCD43A4, 2003193, h16v01

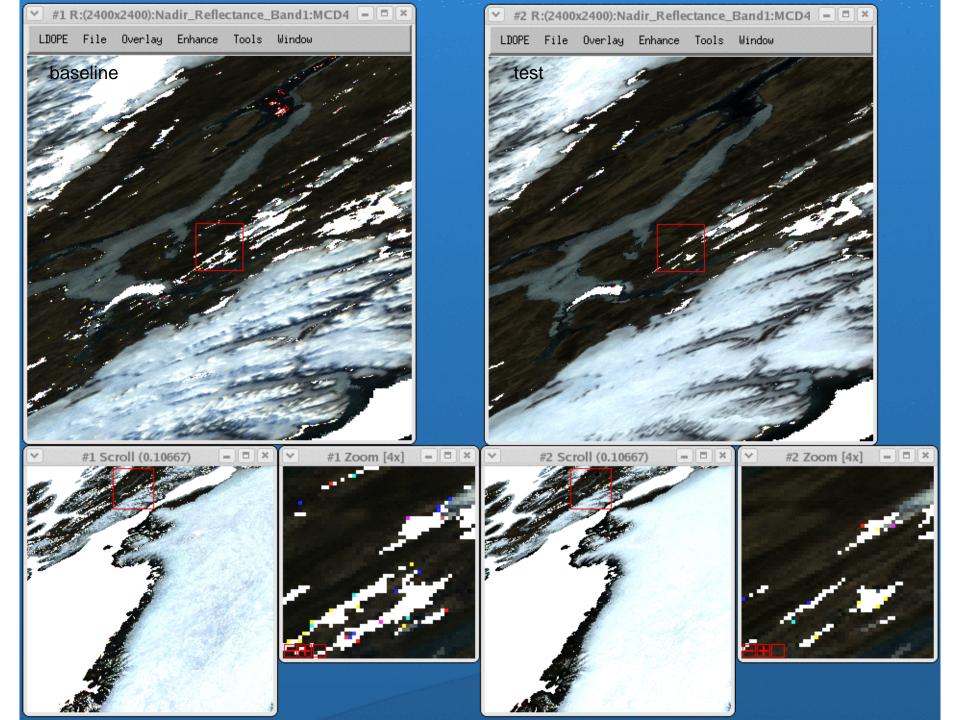
RGB composite from bands 1, 3 and 4

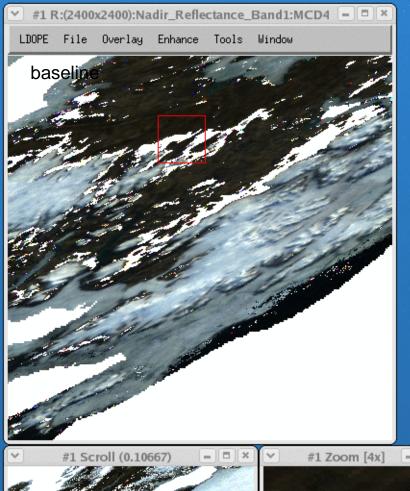


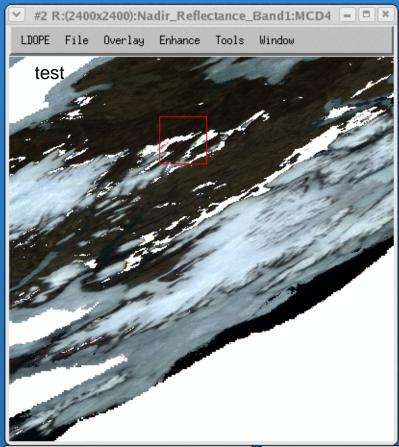


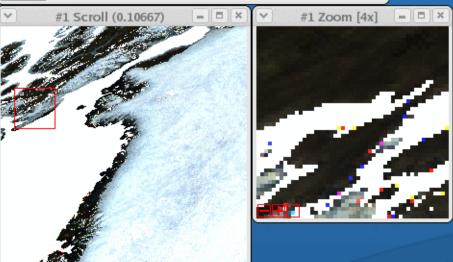
- The test version show significant improvement most likely resulting from use of all the available observation.
- The next slides show different spatial subsets in all cases the new version looks better than the baseline version.

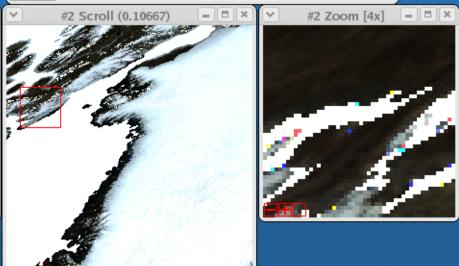


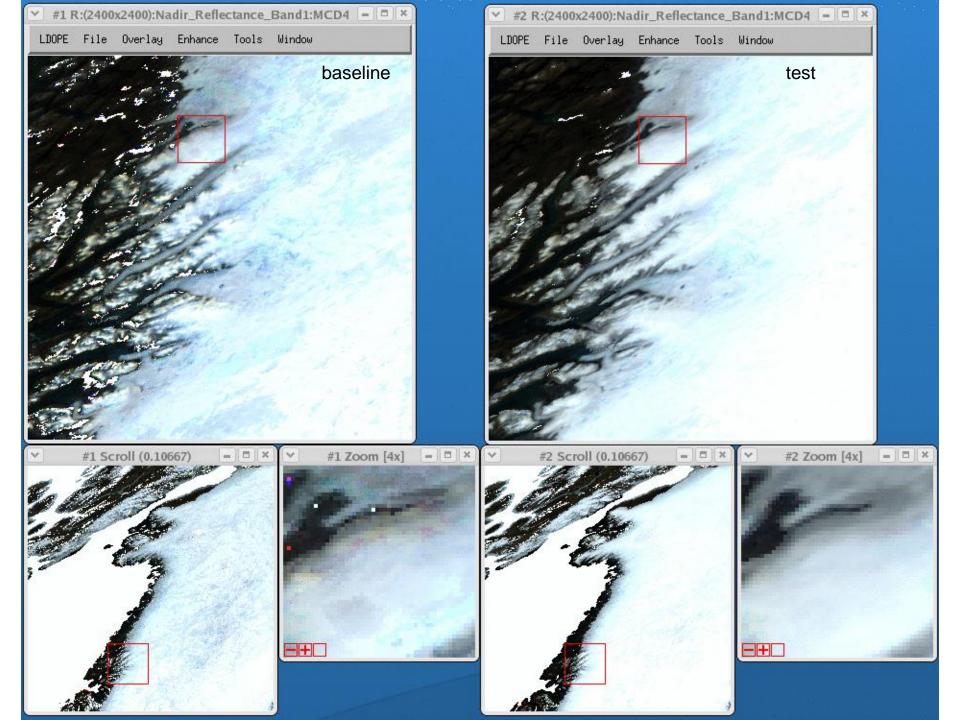


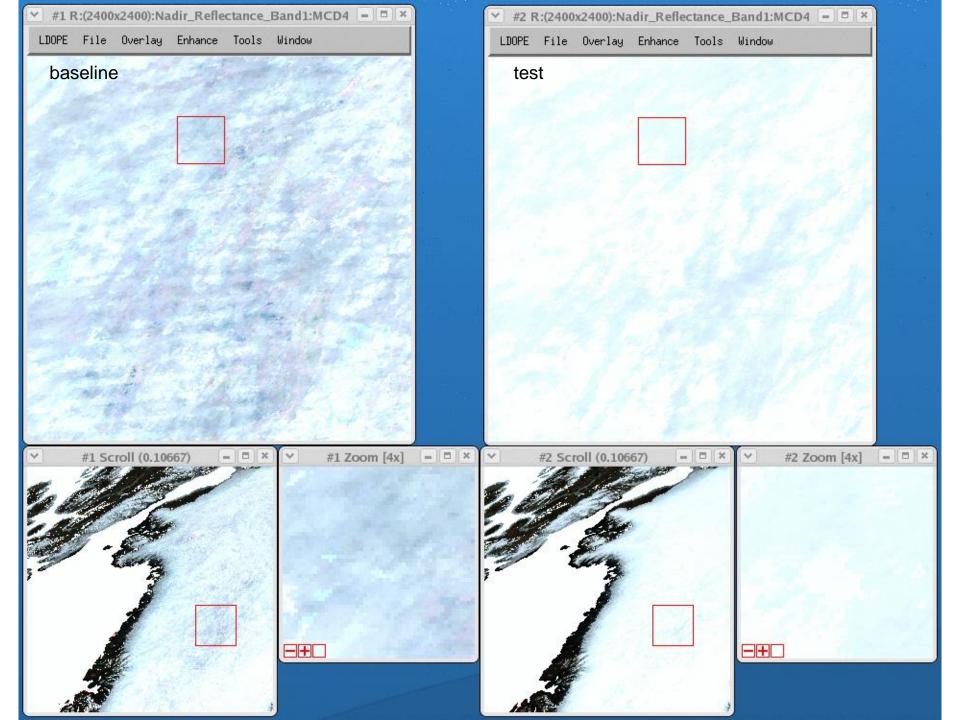












Conclusion (1/3)

- Analysis of MOD09A1 confirms the fix to L2G-lite is working as expected.
- This fix to L2G-lite seems to have improved the quality of the BRDF/Albedo significantly.
- Change in BRDF algorithm to include all available observation has improved the quality of the product at high latitude.
- Some minor issues discovered in the L2G-lite have been already fixed (see the following slides).
 - These changes haven't been tested yet. The 16-day global test will be repeated with some limited evaluation of the test results. These fixes are not expected to make any significant difference to the downstream product quality.

Conclusion (2/3)

- Fill value for QC_500m (MOD09GA)
 - This just needed to be set to 787410671, instead of 0xFFFFFFFF
- Fill value in Band 20 (MODTBGA)
 - Fixed. The values in "fill_out_1km" were a slightly out of order.
- Missing observations along the intersection of the orbits (MOD09GQ)
 - It turns out that all 250m quadrants (pixels) of a 500m grid cell where being set to have the same number of observations as the 500m cell. This turns out not be the case around the edges of a scan. A 250m observation can cover a 500m grid cell in a few quadrants, but does not necessarily cover all 4 quadrants. The nobs is incorrectly set to 0. Also, incorrectly, the nobs for some 250 observations were set to 2, when they should be set to 1. This has been now fixed.

Conclusion (3/3)

- Less number of observations along the edge of the tile (in MOD09GA and MOD09GQ)
 - By observation of Code (Cid Praderas): Nothing wrong here. The 500m pixels are pointing to 1km pixels where the row and offsets are -8 and nobs = 1 (so nothing available in the compact layers). In the 500m Pointer files (MODPTHKM) the "offset_res_1" values are set to 136 and nobs = 1. The 250m pixels have less nobs corresponding to these 500m pixels.
 - Theoretical explanation (Virginia Kalb): An observation is included in a tile grid cell if some specified percentage of the observation overlaps that cell. Along the edges of the tile, it can happen that the 500 meter observation meets that criterion, while its parent 1km observation does not, as the figure shows. The red line is part of the bottom edge of the tile, the dashed rectangle is a 1km observation, and the solid rectangle is a 500 meter observation."

